

Multipath Opportunistic RPL Routing over IEEE 802.15.4

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Motivation

- IPv6 vision of future WSN
(The Internet of Things)
- Relying on two IETF standards:
 - 6LoWPAN
 - RPL
- Majority of the devices running **802.15.4** standard at PHY and MAC level
- Why not combine them and additionally provide QoS?
(not done so far)

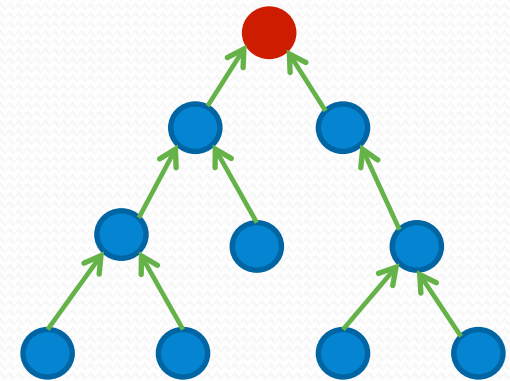


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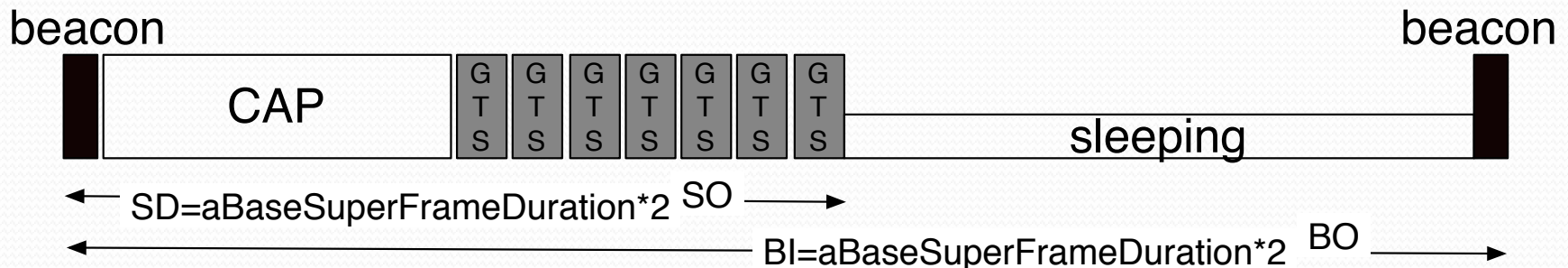
Emerging standards

IEEE 802.15.4.

- **MAC:** beacon(less)
- Topology control:
 - Cluster tree(mesh), star, peer-to-peer
- Beacon **collisions** in basic version

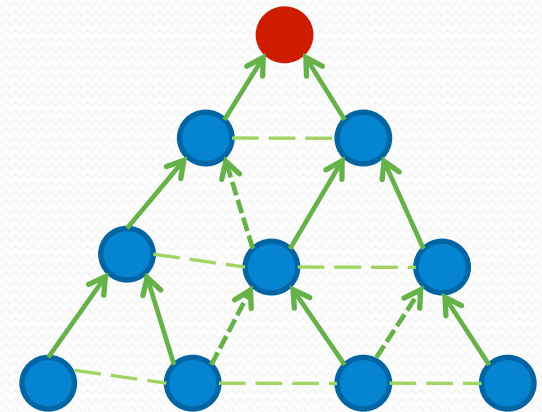


Cluster tree



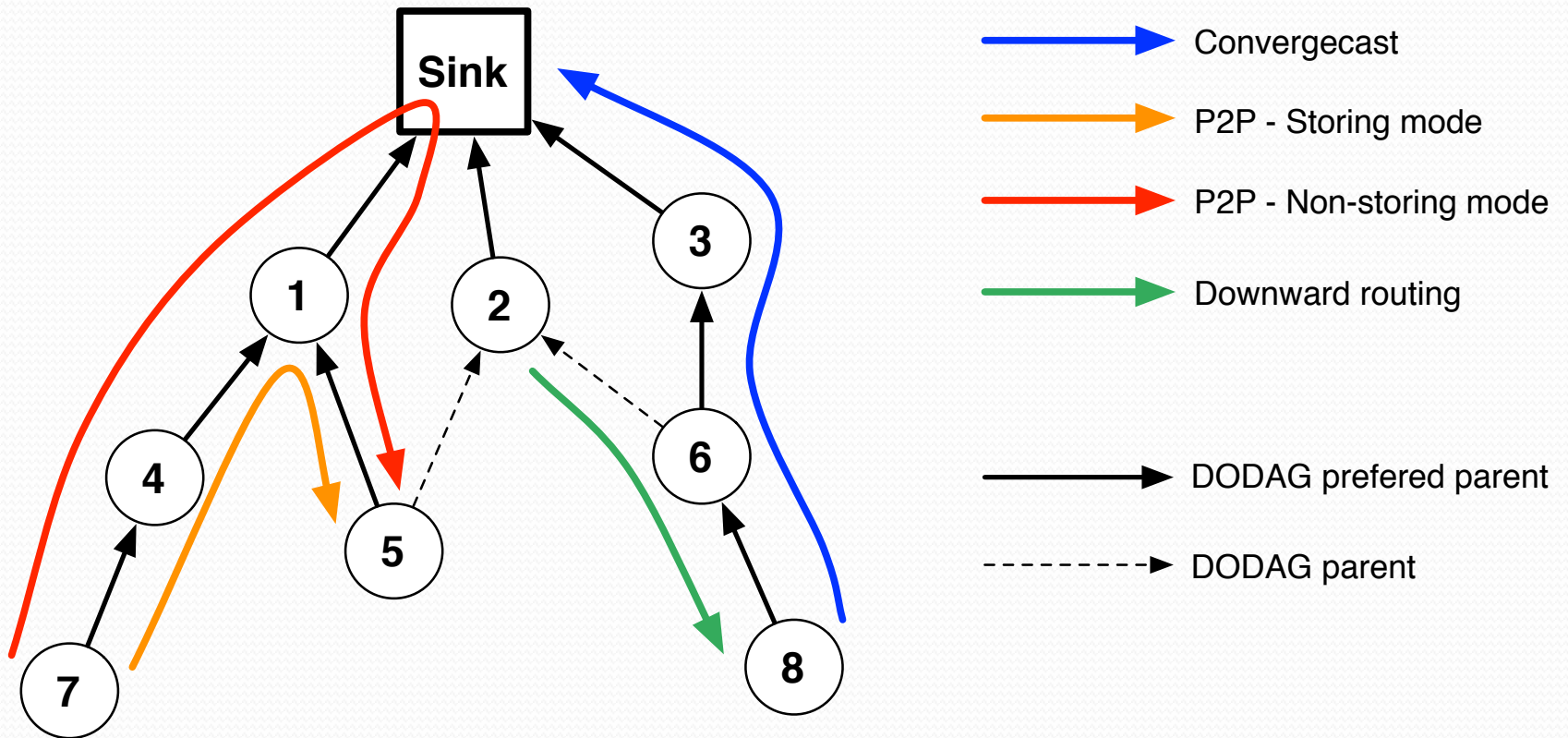
IETF RPL

- **Routing:** Convergecast, downlink traffic, P2P
- Topology control:
Directed Acyclic Graph
1 preferred parent + 2 backup
- DIO (DAG Information Object)
- Trickle Timer
- Supported different metrics: **ETX** (Expected Transmission Count), throughput, latency, ...

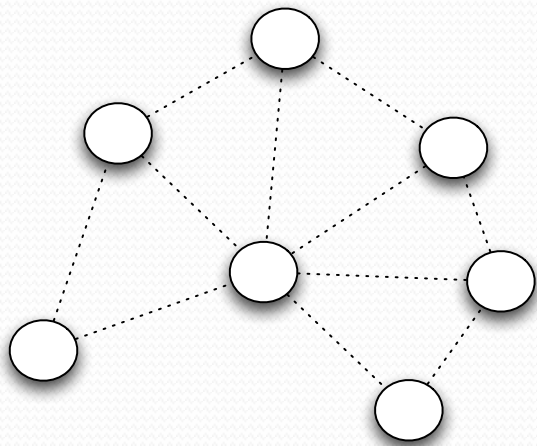


DAG

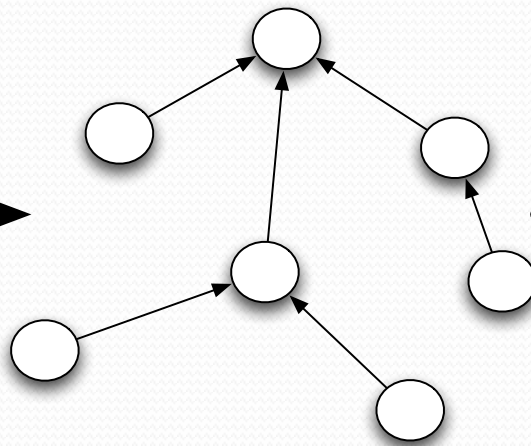
IETF RPL – traffic types



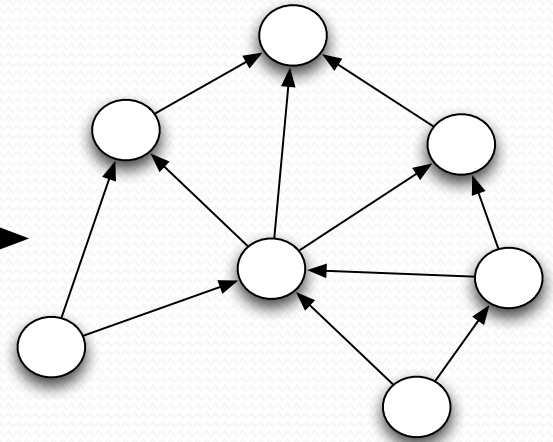
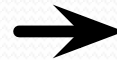
Topology difference



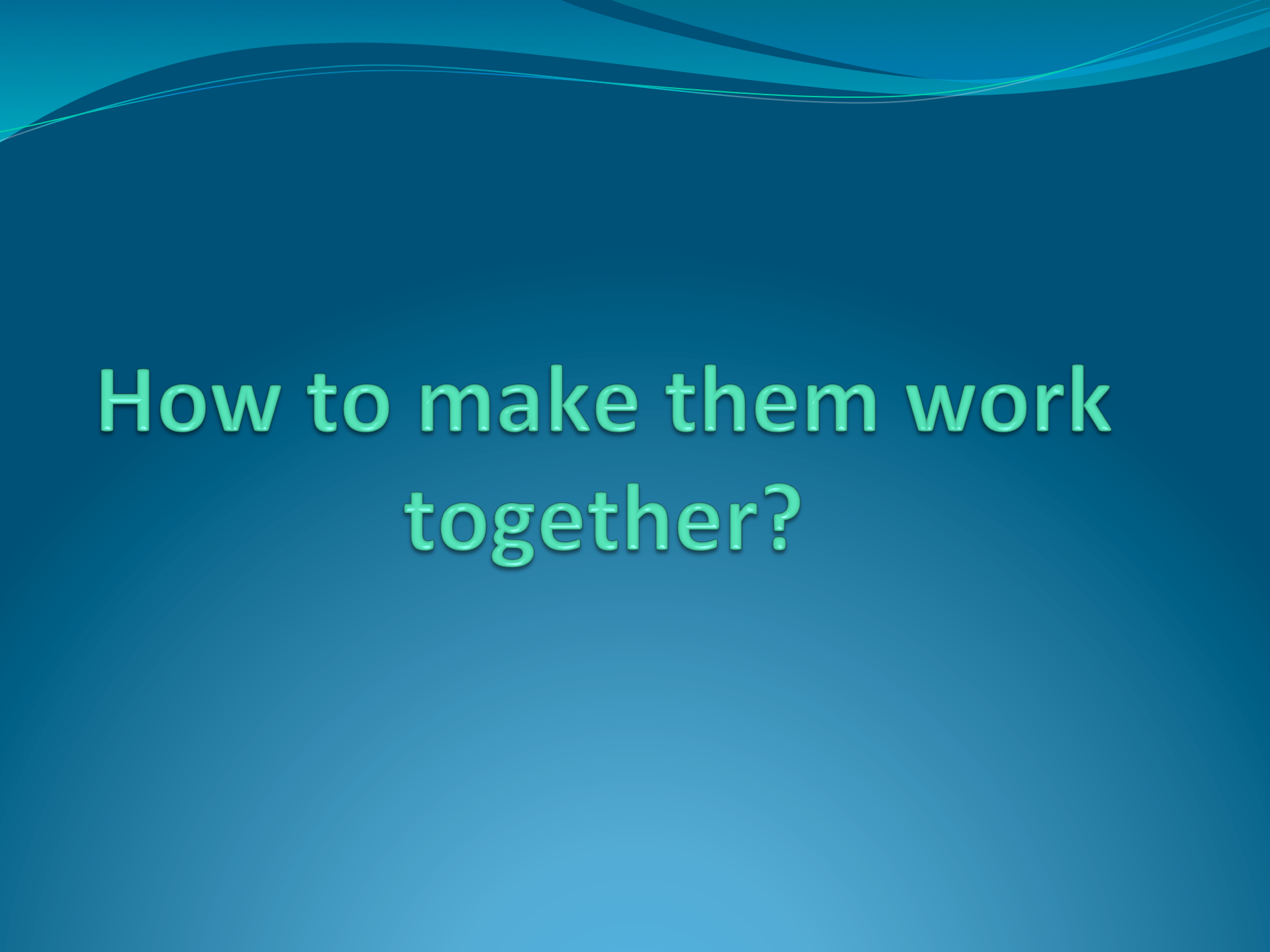
Radio topology



Cluster-Tree
IEEE 802.15.4



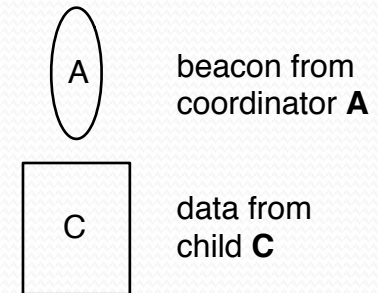
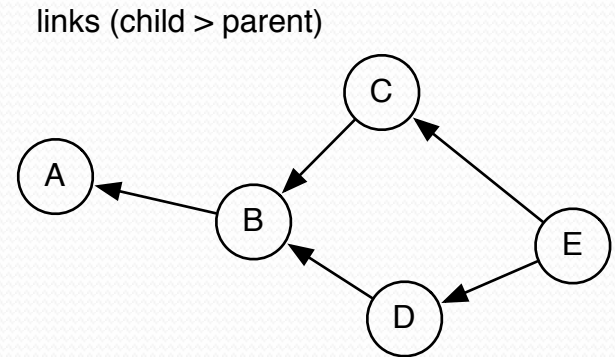
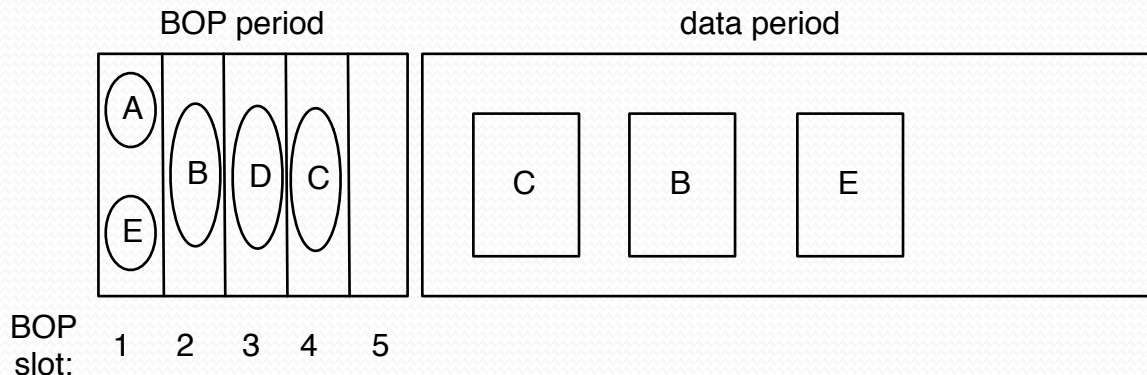
DODAG
RPL



How to make them work
together?

Superframe collision avoidance

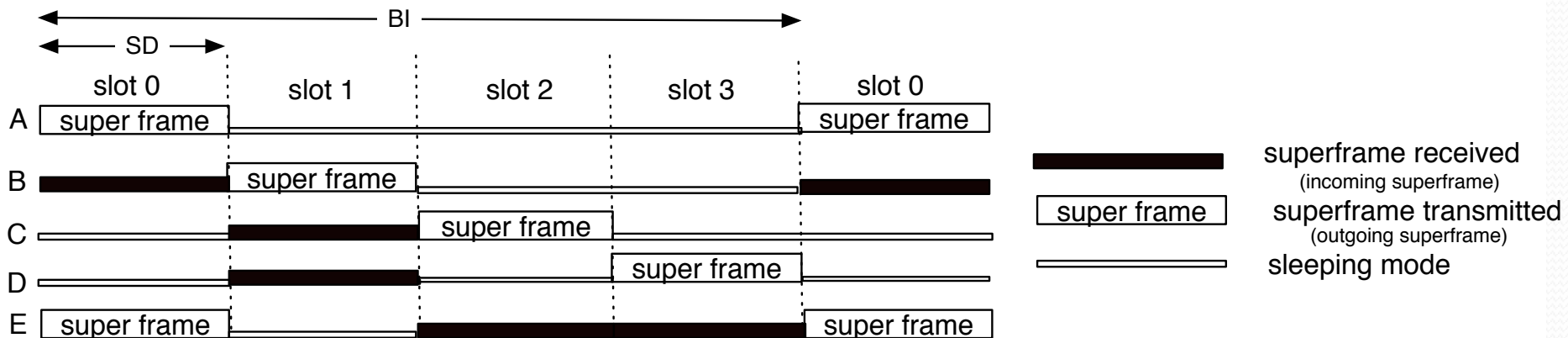
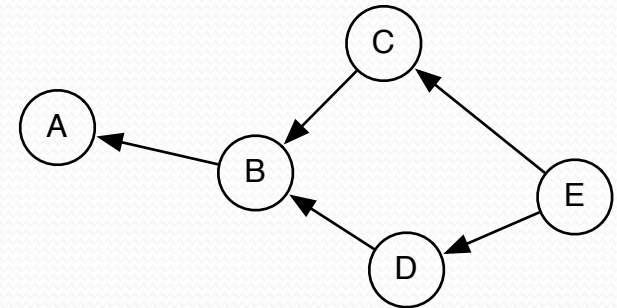
- **Beacon-Only Period (BOP)**
- NO beacon, but data collision remains
- Lower PDR, higher end-to-end delay



Superframe collision avoidance

- **Superframe Scheduling**
- NO beacon, NO data collision
- Higher PDR, lower end-to-end delay
- Less effected by num of neighbors / load

links (child > parent)



B.C. Villaverde, R. De Paz Alberola, S. Rea, and D. Pesch. Experimental evaluation of beacon scheduling mechanisms for multihop IEEE 802.15.4 wireless sensor networks. In International Conference on Sensor Technologies and Applications (SENSORCOMM), pages 226–231. IARIA, July 2010.

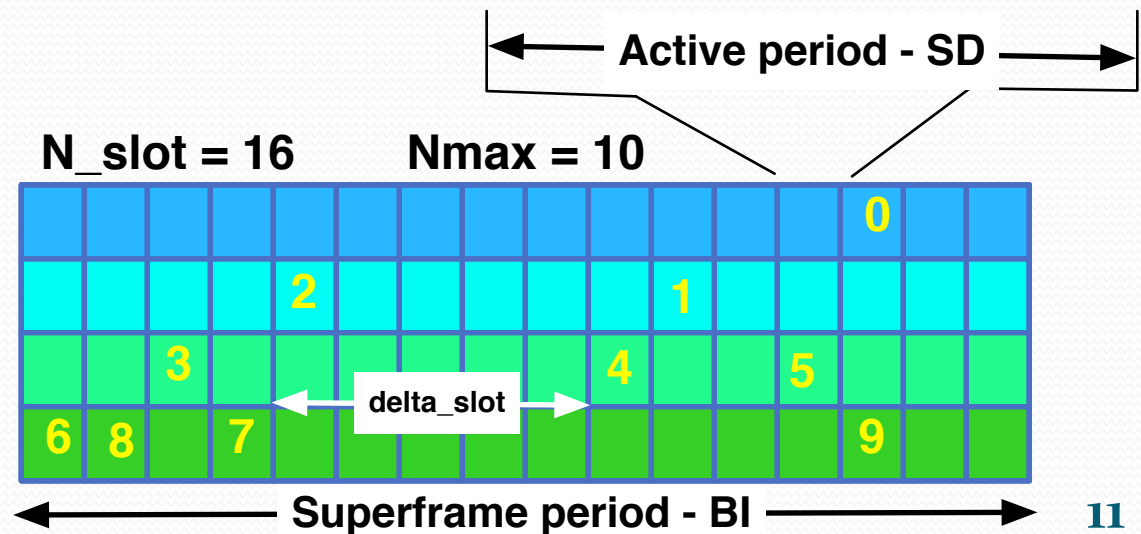
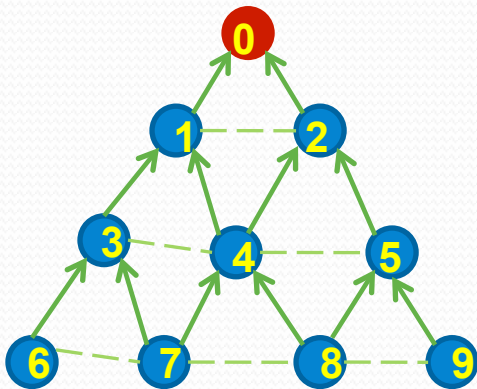
Our improvement

- Slot attribution: random – **accelerate convergence**

- Nmax a priori, same SO and BO

$$N_{\max} + 1 \leq 2^k = N_{\text{slot}} = 2^{BO-SO}$$

- 2-hop neighbor knowledge – *hello msg*
- Adaptable – min change, prudent, DAG consideration
- Example: $N_{\text{slot}} = 16$ & $SD = 150\text{ms} \Rightarrow BI = 2.5\text{s}$



Benefits vs. changes

Benefits

- Accelerate convergence
- Avoid beacon + DATA collisions
- Possibility to follow more parents
- Coexistence of RPL and 802.15.4.

Changes

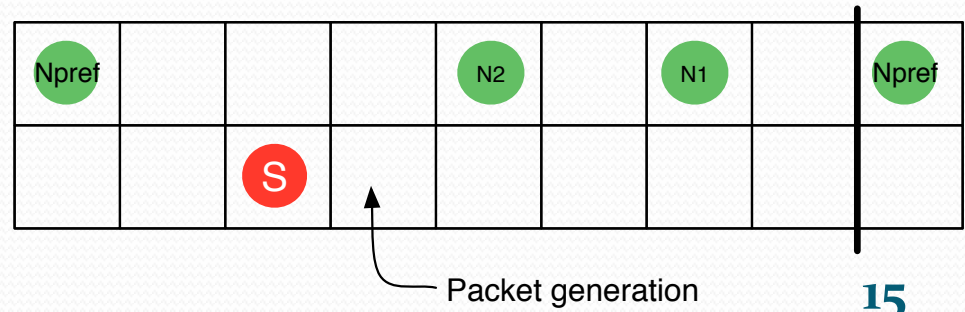
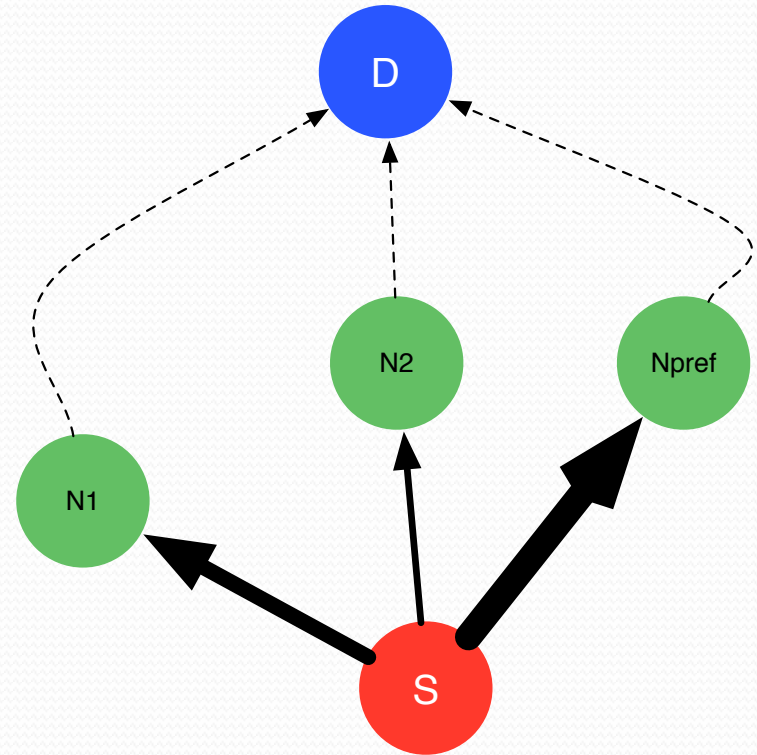
- DIO collated to beacon
- Trickle modification – follow beacon periods
- Clock drift neglected (sync) + OpenWSN Berkley

Opportunistic QoS routing

Basic principles

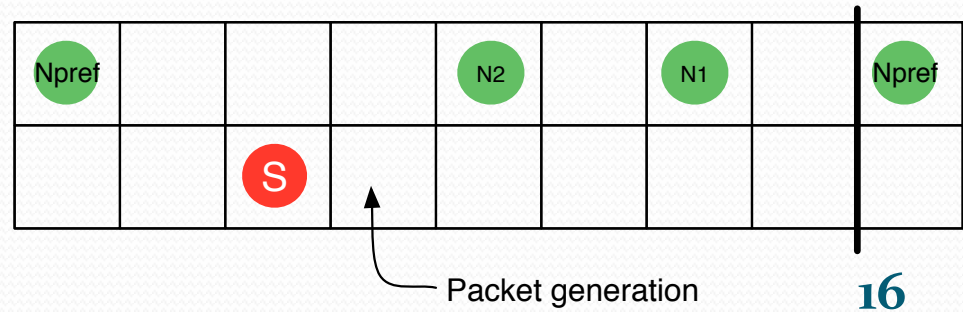
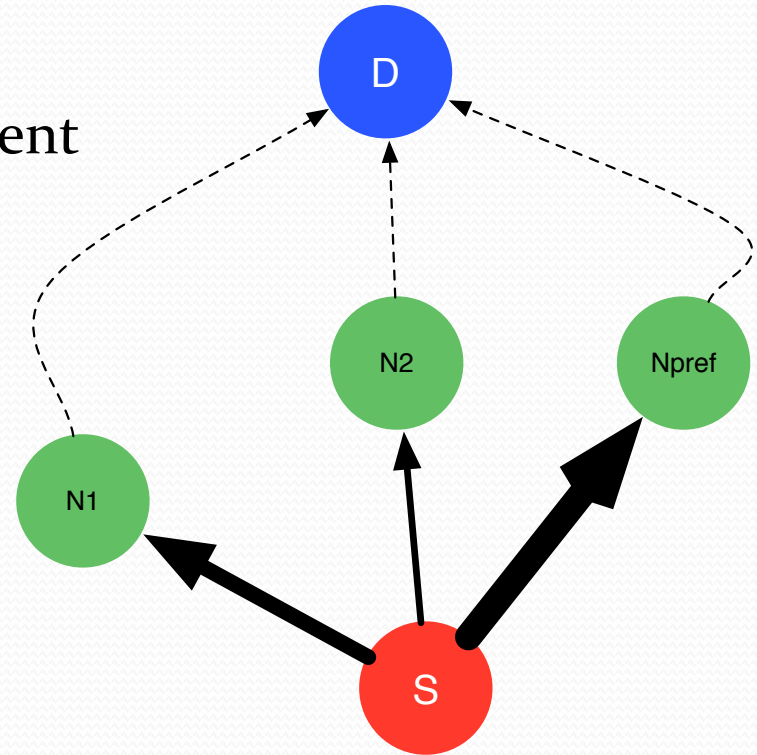
- **Opportunistic multipath routing:** MAC schedule coupled with routing decision, interchangeably use parents
- **QoS:** deadline and energy consumption
- **Packet priority:** best-effort, deadline, min-delay (70 – 20 – 10 %)
- **Queuing** - priority first, deadline first
- **Goals:** minimize overhead (packets / energy) while respecting a max delay
- **DAG metric:** ETX

Forwarding decision - example



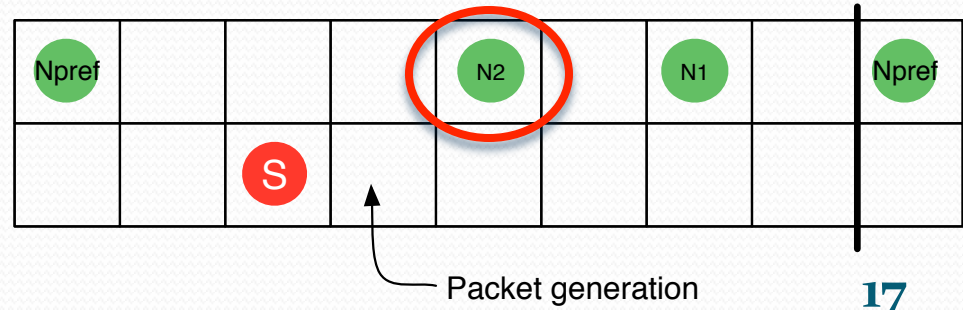
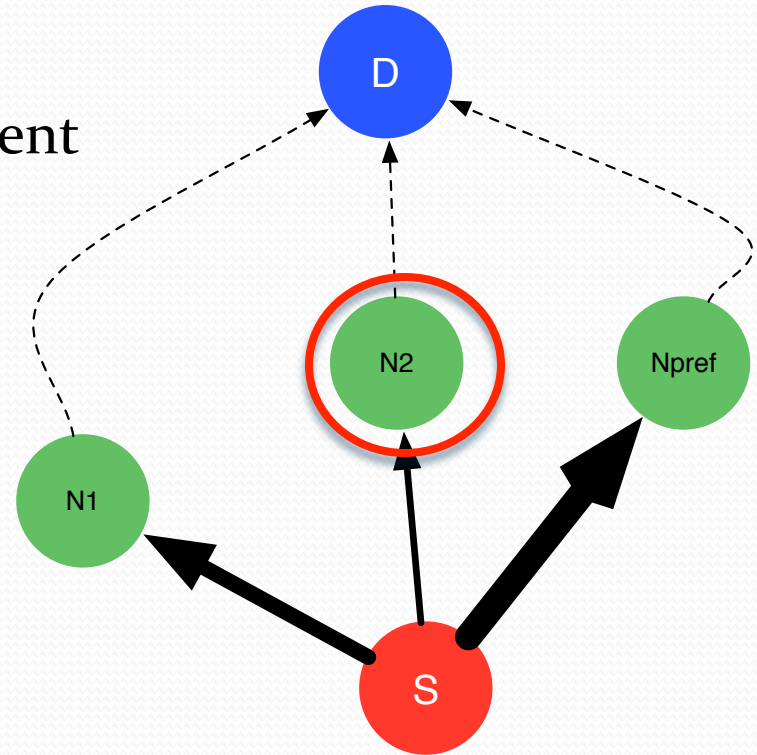
Forwarding decision

- **min-delay** : first available parent



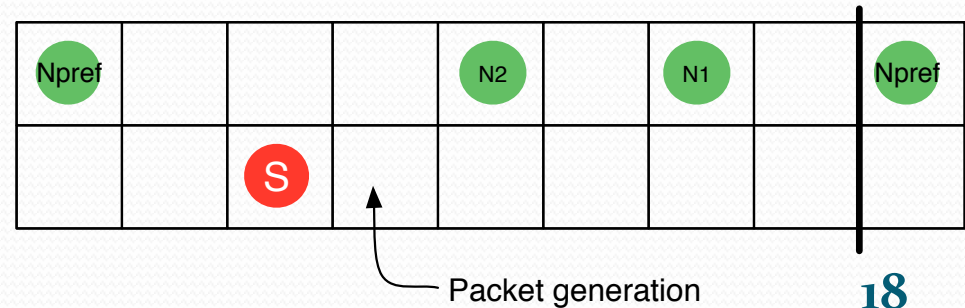
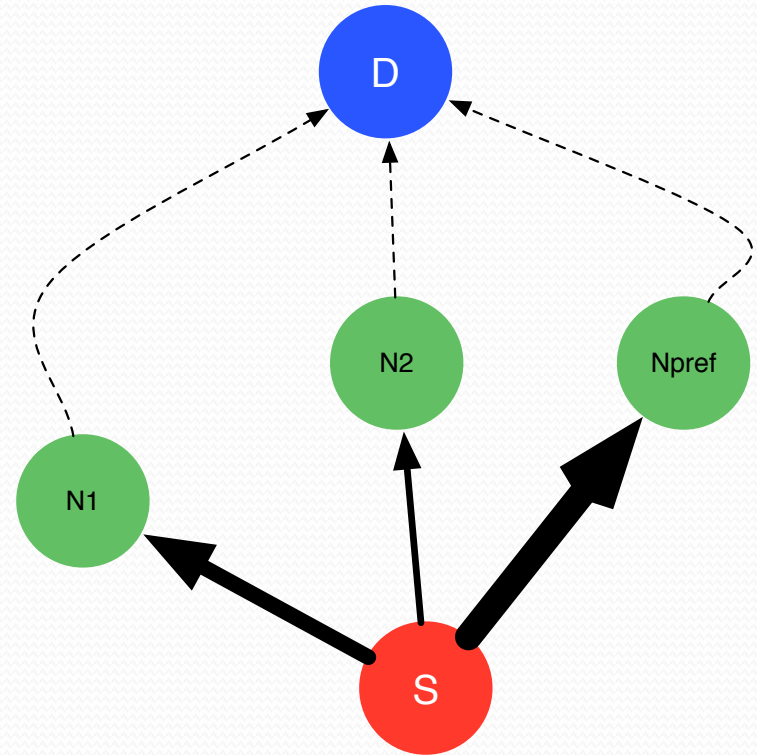
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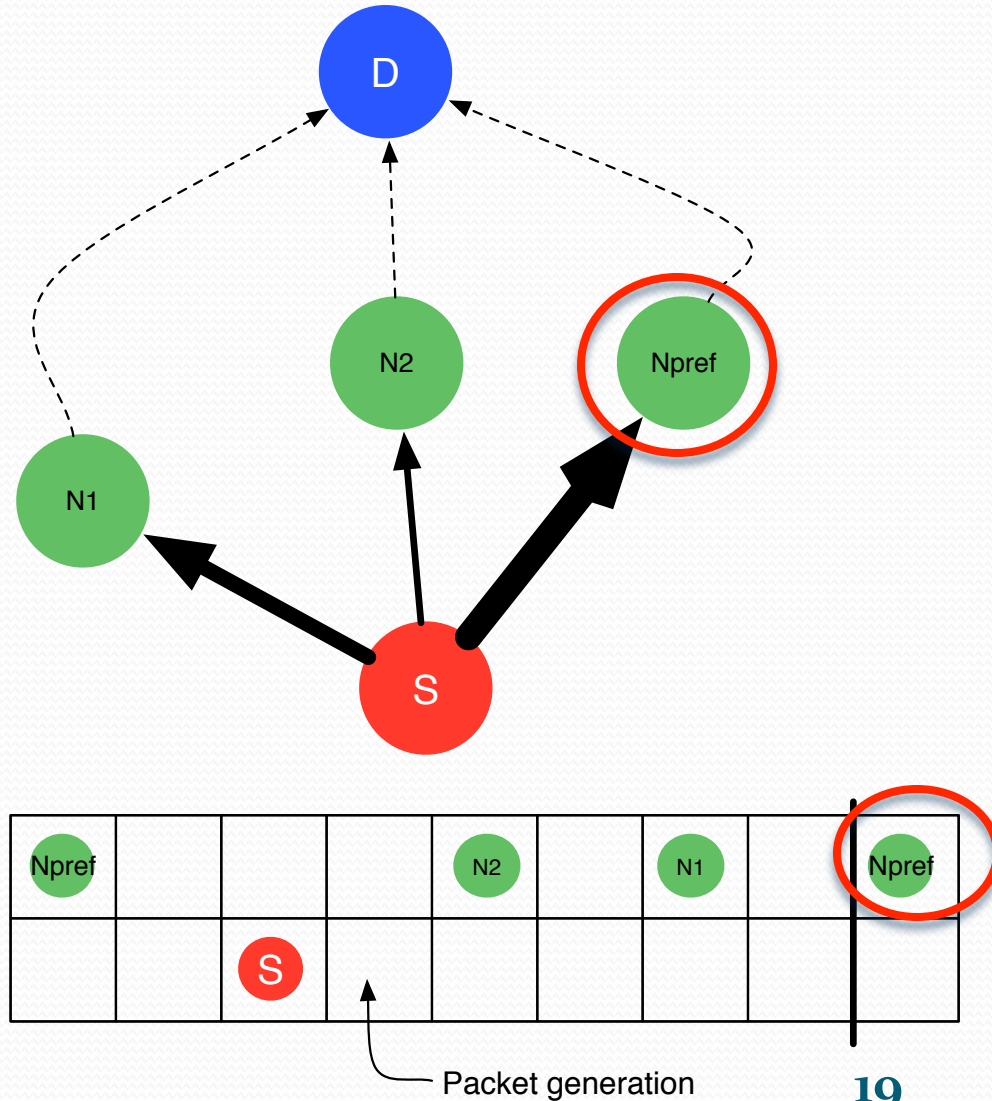
Forwarding decision

- **best effort** : preferred parent
or
parents with same ETX



Forwarding decision

- **best effort** : preferred parent
or
parents with same ETX



Forwarding decision

- **deadline** : respect delay budget and $\Delta ETX \leq 1$
- E2E deadline, step by step delay budget
- Possible candidates:

$$budget = \frac{deadline(p) - t}{d(V)} \geq SD \cdot \Delta_{slot} + BI \cdot \left(\frac{1}{PDR_{beacon}} - 1 \right) + t_{packet} \cdot \frac{1}{PDR_{data}}$$

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$$budget = \frac{deadline(p) - t}{d(V)} \geq \underbrace{SD \cdot \Delta_{slot} + BI \cdot \left(\frac{1}{PDR_{beacon}} - 1 \right)}_{\text{due to beacon loss}} + t_{packet} \cdot \frac{1}{PDR_{data}}$$

due to beacon loss

Forwarding decision

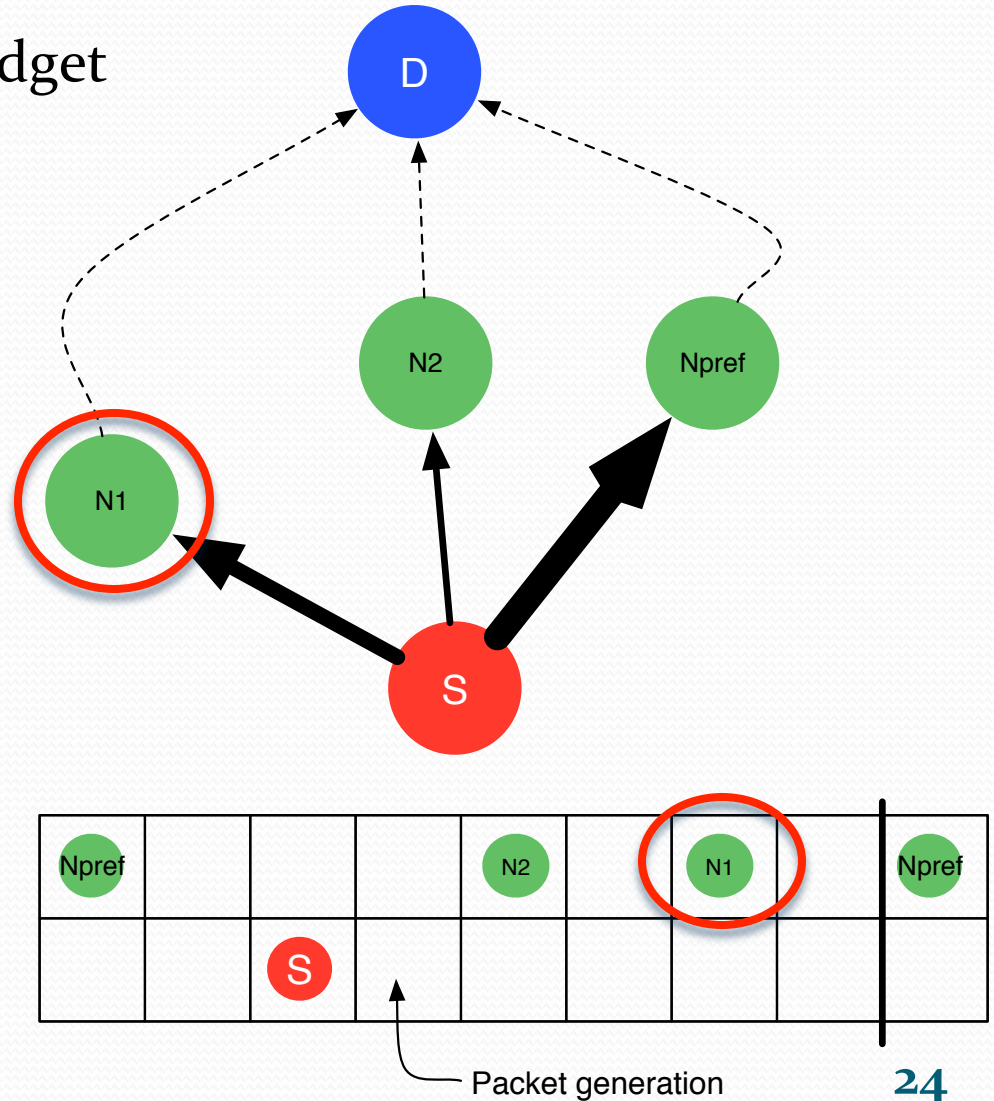
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due to data loss

Forwarding decision

- **deadline** : respect delay budget and $\Delta ETX \leq 1$



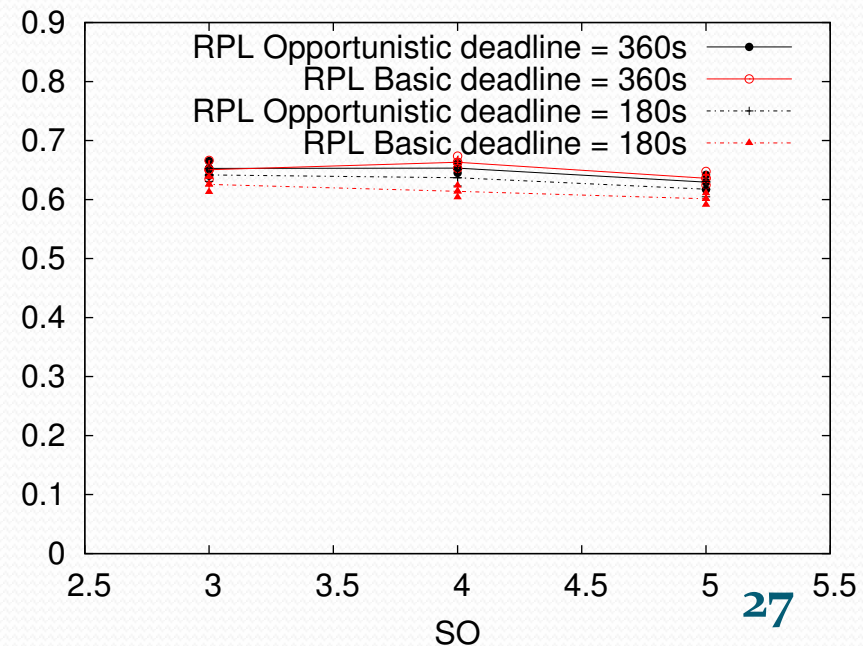
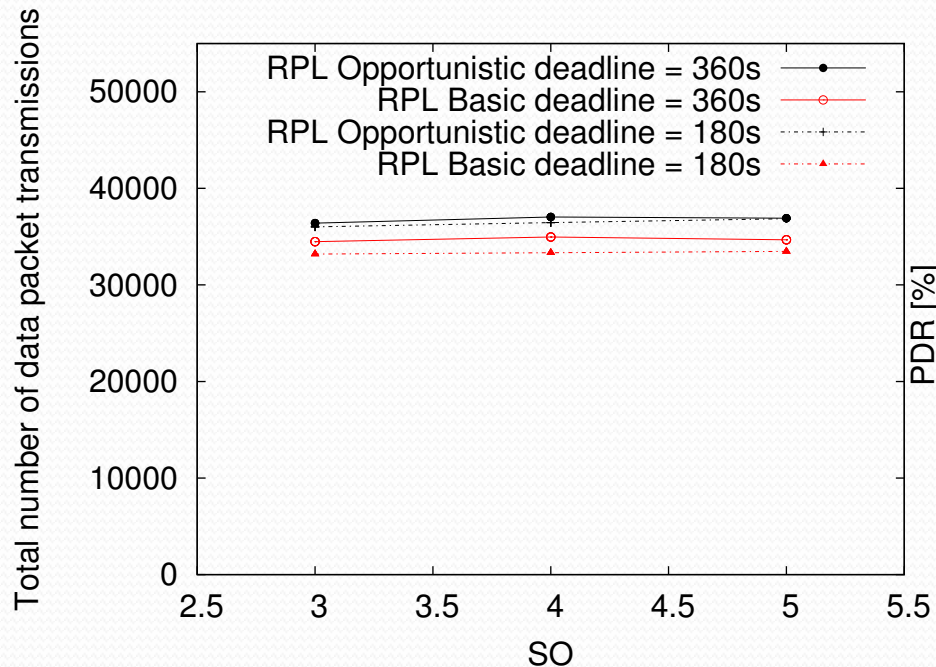
Simulation results

Simulation setup

- WSNNet/Worldsens
- RPL (Contiki implem) & 802.15.4.(LIG – Nazim Abdeddaim)
- 10 random topologies: up to 256 nodes, 400x400 m
- Rayleigh propagation model (not UDG)
- Low intensity traffic: 7.5 min
- Three classes: best-effort, min-delay, deadline (70 – 20 – 10 %)
- SO between 3 and 5
- Duration: 50.000 s

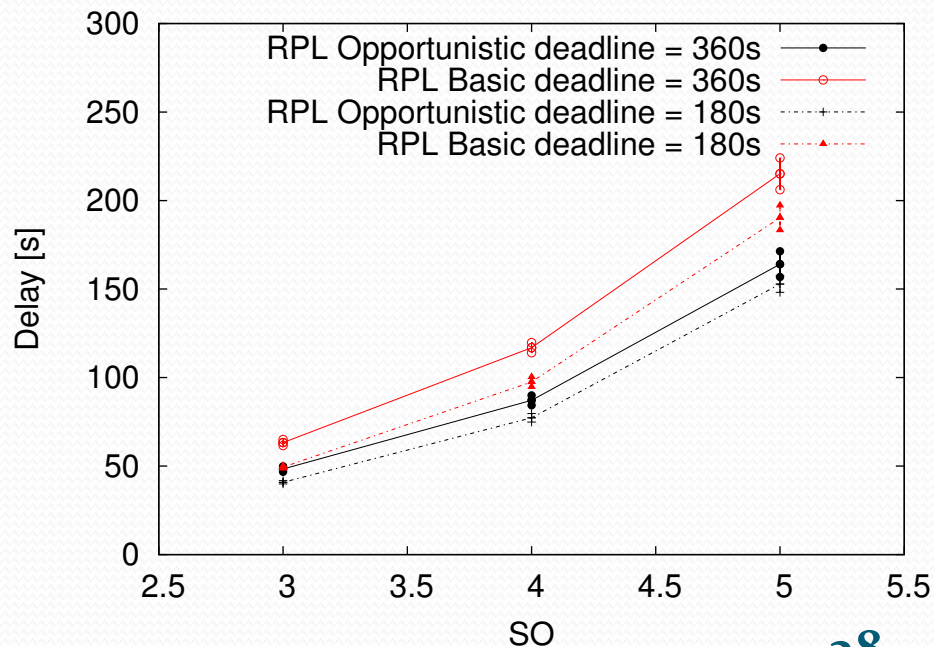
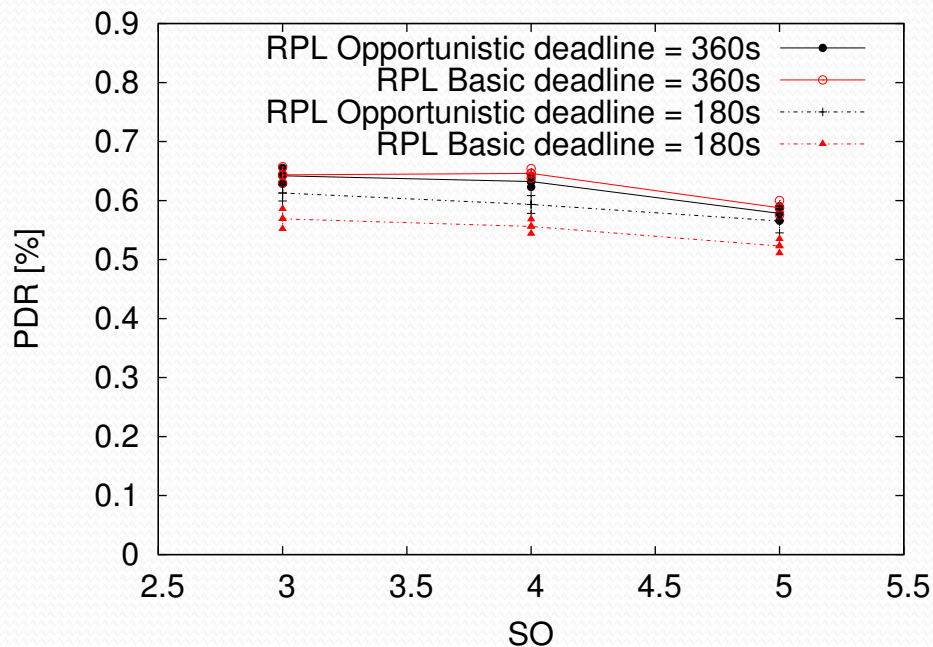
Results – general behavior

- Similar PDR behavior in general, better with shorter deadline criterion
- Slightly greater total number of transmitted packets (+9%)
- Reasonable price for distributing the charge over all possible parents



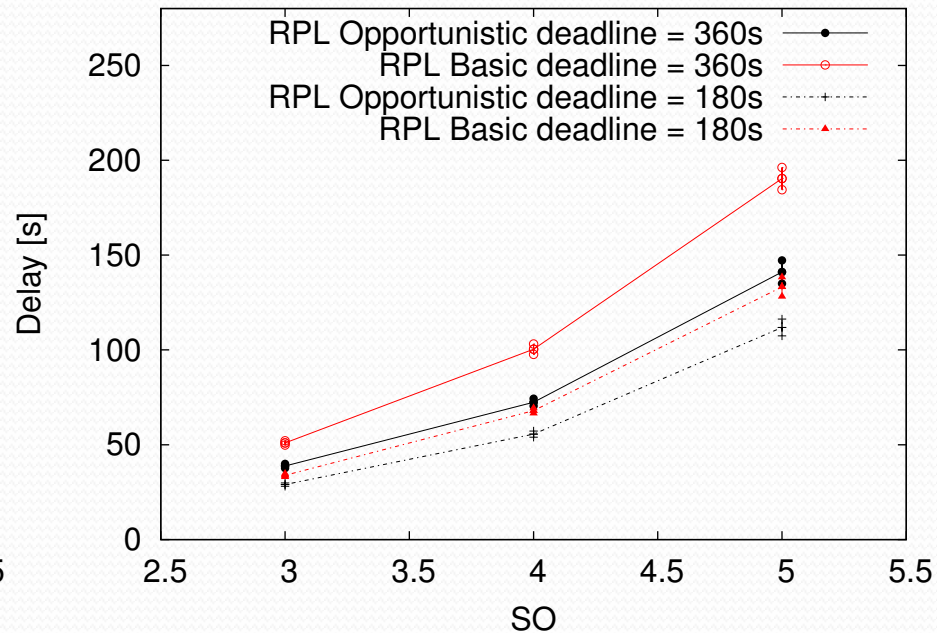
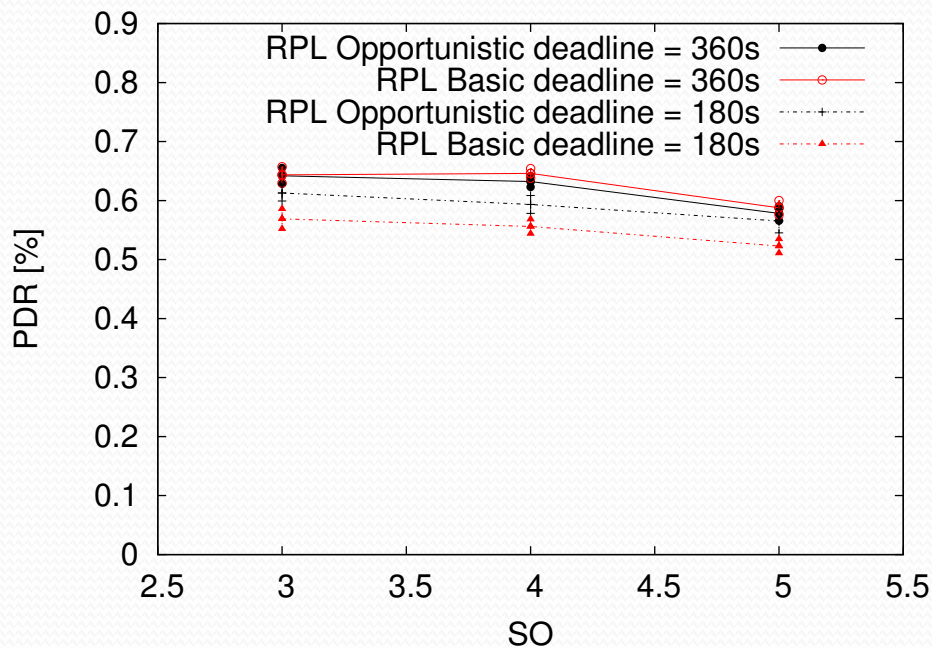
Results – “min-delay” type

- Notable gain in PDR performance with harsh deadline constraints
- Real performance contribution : lower end-to-end delay



Results – “deadline” type

- Similar results – proof of concept



Contributions

- Coexistence of RPL with IEEE 802.15.4. MAC
- Cluster tree adapted to support DAG - multiple parents
- Slightly better PDR and delay results
- Keeping almost the same amount of the generated traffic
- Lower delay incurred even for harsher constraints
- Believe: charge distributed evenly => prolong network lifetime

Future work

- Refine simulation:
 - Verification of charge distribution
 - Limit the packet buffer size
 - Energy consummation (battery level)
 - Tweak MAC parameters to accommodate higher traffic rates
- SensLab experimentations: Contiki RPL + Opportunistic

Questions?

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